

APPLICATION QUESTIONNAIRE ELECTRIC ACTUATOR / ELECTRIC LINEAR DRIVE

Str Cit	stomer: eet: y: Code:	St	ate:		Contac Engineering: Purchasing:	ct Person	Fa		phone #	E-Mai	il
Inc	uiry-no.			Date:		Qua	intity:	Α.	Price Ran		
	mark/App	lication					Linear	Module			Linear Drive
0	Voltage:		DC	:	V Single Ph	ase:	V	Hz	Three Phase	· \	/ Hz
1	Should the Cycles pe		fail-safe to		in position? ow many hours	☐) per day?		☐ no expectatio	on in hours:		
2	-	d speed: sible intermed tion / decele] yes 🔲 no	n/sec n/sec ²		Position	n accuracy:		inch
3	Thrust: Load dire Installation	on position:	lt pushin horizor	g [Static load:] pulling] vertical] at bottom	☐ pushir	b ng and pu ed in an ai	ngle of	uided: [degre ☐ at top	yes [no at bottom
4	Required	stroke:	in	ch		ere vibratio ere vibratio				yes [] no] no
6	Type of r	nounting:	☐ Lateral ☐ Flange ☐ yes		☐ Trunnic	on with brace on with brace Operator wit	ket (fixed) [Rear eye Foot plate k and Mecha	anical Dis	Gimbal Mount
7	Type of p Environn Work pla	protection: nental condi	NEMA tions:		ISO class] dry	Surrour ty	nding tem numid ndoor Class II	perature t	from sical door covered	°F up to corrosive	°F
8	☐ 4 Elec	tronic limit sv tronic limit sv tronic limit sv	vitches (EP	S 04)	n Emitter (EPS		2 Mechani 1 Mechani 3 Mechani	ical limit s	switches	☐ Proxi	ntiometer (1 k Ω) mity switches on Emitter 4 – 20 mA
9	Accessories: Thrust overload protection Variable rod speed Motor integrated frequency inverter Brake Type L (power release) Brake Type B (power set) Hand Release for Brake Other Accessories:						☐ Hi-Temperature Package ☐ Low Temperature Package ☐ Tropical Proof Corrosion Protection Package ☐ Rod End Front Clevis ☐ Motor Control, Position Control, & Integrated Control System ☐ Custom Design, Consult Factory				