

## APPLICATION QUESTIONNAIRE ELECTRIC ACTUATOR / ELECTRIC LINEAR DRIVE

Str Cit	stomer: eet: y: Code:	St	ate:		Cont Engineering: Purchasing:		on	Te Fax:	lephone #	E-Mail	
Inq Pro	uiry-no. oject: mark/Applic			Date:			Quantity:	ear Module	Price Ran Actuator T	ype	Linear Drive
0	Voltage:		DC	): \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	V Single P	hase:	V	Hz	Three Phase		Hz
1	Should the actuator fail-safe to a certain position?										
2	Linear rod Reproducible Acceleration	le intermed			yes 🗌 no	ch / sec o ch / sec²		Positio	on accuracy:		inch
3	Thrust: Load direct Installation Motor posit	position:	It   pushin   horizor   at top	g 🗆	Static load pulling vertical at bottom	□рі	lb ushing and clined in ar age:	pulling	guided: degre □ at top		no at bottom
4	Required s	troke:	in	ch			rations at s rations at o			_	no no
6	Type of mo	_	☐ Lateral☐ Flange☐ yes		Trunn	nion with	bracket (m bracket (fix r with Elect	(ed)	☐ Rear eye ☐ Foot plate ock and Mecha		Gimbal Mount
7	Type of pro Environme Work place Explosion	ntal condi e:			SO class dry	Sui	rrounding to humid indoor Class I	☐ tro	opical   utdoor covered	°F up to corrosive I Group	°F
8	2 Electro 4 Electro 6 Electro	onic limit sv	vitches (EP	PS 04)	n Emitter (EPS	S 06)	4 Mech	nanical limit nanical limit nanical limit	switches	Proximi	ometer (1 k $\Omega$ ) ty switches n Emitter 4 – 20 mA
	Accessorie	☐ Thi ☐ Vai ☐ Mo ☐ Bra ☐ Bra	rust overloa riable rod s otor integrat ake Type L ake Type B nd Release	speed ted freque (power re (power s	ency inverter elease) set)	☐ Low Te ☐ Tropica ☐ Rod Er ☐ Motor (	nd Front Clo Control, Po	Package rrosion Protec evis	& Integrate	ge d Control System	